An Optimal Energy Management System for PV/Battery Standalone System

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ABSTRACT
This paper presents an optimal energy management for PV/battery standalone system. The system comprises photovoltaic array, battery, inverter and AC loads. PV array is an uncontrollable source due to the variations in irradiations and temperature. To deliver the highest point to the load a maximum power point tracking technique is used. In synchronization with battery bank the system becomes controllable. Modes of operation of the system are defined by the battery bank. Modes of operation are based on the difference between supply and load demand. This paper project proposes an optimal energy management strategy to improve the performance of the PV system. The anticipated system performance is evaluated for varying loads in MATLAB/simulink.

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1. INTRODUCTION
Due to critical situation of fossil fuel declining and the global warming effect, alternative energies became popular. In nature many renewable energy resources are available like solar, wind, tidal and hydel. But solar energy is the most popular source among the alternative energy resource with out emission of pollutants energy conversion is done. Demand for solar energy is increased from 20% to 25% over the past 15 years. Other advantages of solar energy are like eco-friendly, abundant availability in nature. Power Electronics palys a major role in this energy management system [1-2]. A power Electronics converter converts the DC power from the PV source into AC power which is used to supply the local loads or to grid [3-5].

Generally a PV cell has low energy conversion efficiency. Its voltage is about 0.5-0.8V, to track the maximum power from photovoltaic maximum power point tracing is essential. Since the PV energy source is discontinuous in nature, to supply power to the load continuously battery is added. Energy can be stored in the battery or it can supply the local load or grid [6-7]. It will define depending upon the different modes of operation. Energy balance between the supply energy and load determines the modes of operation. Bi-directional converter offers the advantages of reducing the no. of batteries used and also ensures the power flow even if one of the cells fails [8].

Energy Management system for controlling a Microgrid is presented in [9]. This paper presents management of power flow for minimizing the cost of electricity and reduction loss of energy produced by renewable energy sources.

Lagorse et al., [10] proposed an Energy Management System to control the energy flow in the microgrid which is composed by PV system, Fuel Cell, supercapacitor and load.

Lu and Francois [11] presents an Energy Management System for a Microgrid based on the day-ahead power scheduling, considering the power prediction and load forecasting.

PSO-Based energy management system for a standalone Microgrid is presented in [12]. In paper describes the optimal balance between generation units and also by incorporating desirable energy objectives into the EMS decision-making process. The modeling equations of the solar cell is shown in [13]

Transformer based isolated bidirectional converter is used the proposed system [14]. Lead-Acid battery is used in the proposed system because of its low cost and long life [15-19]. This paper presents best possible energy management strategy for PV/battery stand-alone system.

The proposed system performance is tested under various operational conditions and obtained results have good energy management characteristics. The rest of the paper is structured as follows: Section 2 discusses about the overall PV/Battery stasalone system description. Section 3 & 4 presents the modeling of the energy management system and different modes of operation respectively. Section 5 validats the proposed energy management control by the simulations results and Section 6 highlights the conclusions drawn from the results.

2. SYSTEM DESCRIPTION

Figure 1 shows the PV/Battery standalone system for energy management system.

![Figure 1. Proposed design of PV/Battery stand-alone system](image)

It includes a Photovoltaic array with buck boost and transformer buck converters, batteries and variable DC load. Buck boost Converter, battery and load are connected through three relays. The proposed system main function is to manage the energy between PV, Battery and load. This energy management is done by the different modes of operation which are resolute by the energy balance between the generated energy and the load demand.

3. MODELING OF PROPOSED SYSTEM

3.1. Dynamic Model of PV Array

The PV array involves N strings of modules connected in parallel, and each string consists of M modules connected in series to obtain a suitable power rating. The dynamic model of PV cell is shown in Figure 2.

![Figure 2. Equivalent electrical circuit for PV cell](image)

The series resistance $R_s$ represents the internal resistance to the current flow. The shunt resistance $R_{sh}$ is inversely related to leakage current to the ground. For an ideal PV cell, $R_s = 0$ (no series loss) and $R_{sh} = \infty$ (no leakage to ground). The typical values of $R_s = 0.05$ to 0.10Ω and $R_{sh} = 200$ to 300 Ω. The energy
conversion efficiency of PV cell is sensitive to small variations in $R_S$, but is insensitive to variations in $R_{Sh}$. A small increase in $R_S$ can decrease the PV output significantly.

The process of modeling of solar cell is developed based on the following equations [13]. The output-terminal current $I$ is equal to

$$ I = I_{ph} - I_d - I_{sh} $$

where,
- $I_{ph}$: Light generated current
- $I_d$: Diode Current
- $I_{sh}$: Shunt Leakage current

$$ I = I_{ph} - I_{oc} * \frac{qV_P}{kT} - 1 $$

where,
- $I_{oc}$: Reverse saturation current of the diode [A].
- $q$: Electron charge [1.60217646×10$^{-19}$c].
- $k$: Boltzmann constant [1.3806503×10$^{-23}$J/k].
- $T$: Temperature of the p-n junction.
- $\alpha$: Diode identity factor which lies between 1 & 2 for monocrystalline silicon.

### 3.2. MPPT During DC-DC Conversion

The PV cell produces the maximum power at voltage corresponding to the knee point of the $I$-$V$ curve, as shown in Figure 3.

![Figure 3. MPPT System](image)

$V_{max}$ and $I_{max}$ are maximum power point voltage and current, respectively. The dc-dc converter is set to operate at optimal voltage to achieve maximum power by MPPT algorithm. In this system Perturb and Observe (P&O) method is used to track the MPP from PV cell.

P&O measures and operates by increasing or decreasing the array terminal voltage, or current, at regular intervals and then comparing the PV output power with that of the previous sample point. If the PV array operating voltage changes and power increases ($dP/dV$, PV > 0), the control system adjust the PV array operating point in that direction; otherwise the operating point is moved in the opposite direction.

### 3.3. Electrical Model of Battery

Battery is an important element of a stand-alone PV system due to the fluctuating nature of PV array. Lead acid battery is used due to its performance characteristics [19] as shown in Figure 4.

![Figure 4. Equivalent Circuit of Battery.](image)
Electromagnetic force is kept in series with the source voltage $E_b$. Internal resistance $R_b$. The terminal voltage of the battery is given by:

$$V_{batt} = E_b - R_b*{I_{batt}} - V_{cb} \tag{2}$$

State of charge of the battery is given in the equation below:

$$SOC = 1 - \frac{Q_d}{C_{batt}} = 1 - \frac{I_{batt}*t}{C_{batt}} \tag{3}$$

where,

- $Q_d$ : ampere-hours stored in the battery during a time $t$ with a charging current $I_{batt}$.
- $C_{batt}$ : battery nominal capacity.

### 3.4. Bidirectional DC-DC Converter

Transformer based isolated bidirectional converter is shown in Figure 5.

![Figure 5. Transformer Based Isolated DC-DC Converter](image)

Isolated buck is used due to its advantages over other converters. It has the following features. To convert the energy storage system to the bus. It is able to operate under a wider output power range. Bidirectional power flow, high power operation, galvamic isolation, long battery life time. A long battery life time is achieved by draining from and providing to the battery a low ripple DC Current.

### 4. MODES OF OPERATION OF PROPOSED SYSTEM

The energy management is done between the PV system, Battery and Load. This management system controls the energy produced by the PV array and battery storage to supply the demand [21-22].

#### 4.1. Operating Modes

The proposed PV/Battery stand alone system operates in any one of the five modes.

**Mode 1:** $P_{PV} > P_{load}$ (Battery Charging) : In this mode PV system generates excess amount of power than the demand. At this time battery is charging with remaining power.

**Mode 2:** $P_{PV} < P_{load}$ (Battery Discharging): In this mode PV system generates insufficient power and the required amount of power is taken from the battery.

**Mode 3:** $P_{PV} = 0$ (Battery supplies to load): When there is no available energy from the PV then Battery supplies the load

**Mode 4:** $P_{PV} = P_{load}$ (Only PV supplies to load): In this mode the PV array generate sufficient energy to feed the load without the interference of battery.

**Mode 5:** $P_{PV} = 0, P_{batt} = 0$ (Disconnect the load) In this mode, no PV energy production and battery is completely discharged, then the consumer is disconnected.

#### 4.2. Simulation Circuit Diagram

Figure 6 shows the simulation diagram for proposed energy management system. The proposed system consists of PV array, Battery and Energy Management System. PV array system will act as a source and battery will charge and discharge depending on the load. This energy management is done by the
different modes of operation which are resolute by the energy balance between the generated energy and the load demand.

![Figure 6. Simulation Diagram for Proposed System](image)

**4.3. Proposed Algorithm for Energy Management System**

```matlab
function [R2, R1, R3] = fcn(Vbattery, Ppv, Plo)
    R1 = 0; R2 = 0; R3 = 0;
    Pav = 0;
    Vhvd = 190;
    Vlvd = 100;
    Pav = Ppv - Plo;
    if Pav > 0
        if Vbattery < Vhvd
            R1 = 1;
            R2 = 1;
            R3 = 0;
        else
            R1 = 0;
            R2 = 1;
            R3 = 0;
        end
    else
        if Vbattery > Vlvd
            R1 = 0;
            R2 = 1;
            R3 = 1;
        else
            R1 = 0;
            R2 = 0;
            R3 = 0;
        end
    end
end
```

**5. SIMULATION RESULTS**

The Figure 7 shows the power-time characteristics, where the rise time is from 0 to 0.2 sec, transient state starts from 0.2 to 0.6 sec and from 0.6 to 1 it shows the steady state.

Load characteristics are shown in the Figure 8 where the curves are plotted between Voltage and time, current and time, power and time. The raise time is from 0 to 0.11, transient state is from 0.12 to 0.5 sec and the steady state characteristics are from 0.5 to 1 sec as shown here.
Figure 7. PV Power v/s Time  

Figure 8. Load Characteristics

Figure 9 shows PV characteristics which are plotted between the Voltage and time, current and time, power and time. The rise time is from 0 to 0.14, transient state is from 0.15 to 0.6 sec and the steady state characteristics are from 0.61 to 1 sec shown here.

Figure 10 shows characteristics of DC Converter, which are plotted between the Voltage and time, current and time, power and time. The raise time starts from 0 to 0.14, transient state is from 0.15 to 0.7 sec and the steady state characteristics are from 0.7 to 1 sec shown here.

6. CONCLUSION

An optimal energy management algorithm was developed for PV/battery stand-alone system. The algorithm has capable to manage and organize the different modes of operation. The modeling of PV cell is studied with the MPPT technique. Battery is connected with bi-directional DC-DC converter to compensate the load. The simulation result shows the energy management algorithm will operate correctly for the battery charging and discharging and in compensation of the load demand.

REFERENCES


