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1. **INTRODUCTION (10 PT)**

The main text format consists of a flat left-right columns on A4 paper (quarto). The margin text from the left and top are 2.5 cm, right and bottom are 2 cm. The manuscript is written in Microsoft Word, single space, Time New Roman 10 pt, and maximum 12 pages for original research article, or maximum 16 pages for review/survey paper, which can be downloaded at the website: http://ijra.iaescore.com.

A title of article should be the fewest possible words that accurately describe the content of the paper. The title should be succinct and informative and no more than about 12 words in length. Do not use acronyms or abbreviations in your title and do not mention the method you used, unless your paper reports on the development of a new method. Titles are often used in information-retrieval systems. Avoid writing long formulas with subscripts in the title. Omit all waste words such as "*A study of ...*", "*Investigations of ...*", "*Implementation of ...*”, "*Observations on ...*", "*Effect of.....*", “*Analysis of …*”, “Design of…”, etc.

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4. Results and Discussion, and 5. Conclusion.** The structure is well-known as **IMRaD** style.

Literature review that has been done author used in the section "INTRODUCTION" to explain
the difference of the manuscript with other papers, that it is innovative, it are used in the section "RESEARCH METHOD" to describe the step of research and used in the section "RESULTS AND DISCUSSION" to support the analysis of the results [2]. If the manuscript was written really have high originality, which proposed a new method or algorithm, the additional section after the "INTRODUCTION" section and before the "RESEARCH METHOD" section can be added to explain briefly the theory and/or the proposed method/algorithm [4].

1. **METHOD (10 PT)**

Explaining research chronological, including research design, research procedure (in the form of algorithms, Pseudocode or other), how to test and data acquisition [5]–[7]. The description of the course of research should be supported references, so the explanation can be accepted scientifically [3], [4] Figures 1-2 and Table 1 are presented center, as shown below and cited in the manuscript [5], [8]–[13]. Figure 1(a) shown energy consumption simulated by MATLAB-ADAMS. Figure 1(b) shown energy consumption calculated dynamics.

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| (a) | (b) |
| Figure 1. Energy consumption of three gaits: (a) ADAMS simulation (two strides: 0.08 m and 0.10 m) and (b) calculated through our dynamics model (strides: 0.08 m)Table 1. The performance of ...

|  |  |  |
| --- | --- | --- |
| Variable | Speed (rpm) | Power (kW) |
| x | 10 | 8.6 |
| y | 15 | 12.4 |
| z | 20 | 15.3 |

 |



Figure 2. Robot model

1. **RESULTS AND DISCUSSION (10 PT)**

In this section, it is explained the results of research and at the same time is given
the comprehensive discussion. Results can be presented in figures, graphs, tables and others that make
the reader understand easily [14], [15]. The discussion can be made in several sub-sections.

**3.1. Sub section 1**

Equations should be placed at the center of the line and provided consecutively with equation numbers in parentheses flushed to the right margin, as in (1). The use of Microsoft Equation Editor or MathType is preferred.

$E\_{v}-E=\frac{h}{2.m} (k\_{x}^{2}+k\_{y}^{2}$) (1)

All symbols that have been used in the equations should be defined in the following text.

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3.2.1. Subsub section 1

yy

3.2.2. Subsub section 2

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1. **CONCLUSION (10 PT)**

Provide a statement that what is expected, as stated in the "INTRODUCTION" section can ultimately result in "RESULTS AND DISCUSSION" section, so there is compatibility. Moreover, it can also be added the prospect of the development of research results and application prospects of further studies into the next (based on result and discussion).

**ACKNOWLEDGEMENTS (10 PT)**

Author thanks ... . In most cases, sponsor and financial support acknowledgments.

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The main references are international journals and proceedings. All references should be to the most pertinent, up-to-date sources **and the minimum of references** are **25 entries** (for original research paper)and **50 entries** (for review/survey paper). References are written in **IEEE style**. For more complete guide can be accessed at (http://ipmuonline.com/guide/refstyle.pdf). Use of a tool such as **EndNote**, **Mendeley**, or **Zotero** for reference management and formatting, and choose **IEEE style**. Please use a consistent format for references-see examples (8 pt):

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* R. Fardel, M. Nagel, F. Nuesch, T. Lippert, and A. Wokaun, “Fabrication of organic light emitting diode pixels by laser-assisted forward transfer,” *Appl. Phys. Lett.*, vol. 91, no. 6, Aug. 2007, Art. no. 061103, doi: 10.1063/1.2759475.
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* G. Veruggio, “The EURON roboethics roadmap,” in *Proc. Humanoids ’06: 6th IEEE-RAS Int. Conf. Humanoid Robots*, 2006, pp. 612–617, doi: 10.1109/ICHR.2006.321337.
* J. Zhao, G. Sun, G. H. Loh, and Y. Xie, “Energy-efficient GPU design with reconfigurable in-package graphics memory,” in *Proc. ACM/IEEE Int. Symp. Low Power Electron. Design (ISLPED)*, Jul. 2012, pp. 403–408, doi: 10.1145/2333660.2333752.
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J. K. Author, “Title of chapter in the book,” in *Title of His Published Book*, X. Editor, Ed., *x*th ed. City of Publisher, State (only U.S.), Country: Abbrev. of Publisher, year, ch. *x*, sec. *x*, pp. *xxx–xxx.*

*Examples:*

* A. Taflove, *Computational Electrodynamics: The Finite-Difference Time-Domain Method* in Computational Electrodynamics II, vol. 3, 2nd ed. Norwood, MA, USA: Artech House, 1996.
* R. L. Myer, “Parametric oscillators and nonlinear materials,” in *Nonlinear Optics*, vol. 4, P. G. Harper and B. S. Wherret, Eds., San Francisco, CA, USA: Academic, 1977, pp. 47–160.
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\*In the reference list, however, list all the authors for up to six authors. Use *et al.* only if: 1) The names are not given and 2) List of authors more than 6. *Example*: J. D. Bellamy *et al.*, Computer Telephony Integration, New York: Wiley, 2010.

*See the examples:*

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**BIOGRAPHIES OF AUTHORS (10 PT)**

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|  | **Neil Bose**     is the Vice President (Research) at Memorial University, Newfoundland and Labrador‟s University. Previously he was Principal of the Australian Maritime College (AMC), a specialist institute of the University of Tasmania, and a Professor of Maritime Hydrodynamics. Neil obtained his B.Sc. in NavalArchitecture and Ocean Engineering from the University of Glasgow in 1978 and his Ph.D. also from Glasgow in 1982. He came to AMC in Tasmania in May 2007 as the Manager of the Australian Maritime Hydrodynamics Research Centre. His personal research interests are in marine propulsion, autonomous underwater vehicles, ocean environmental monitoring, ocean renewable energy, ice/propeller interaction and aspects of offshore design. Neil Bose is an ocean engineer and naval architect with an international reputation in marine propulsion built up through close collaboration with international industry. He can be contacted at email: nbose@mun.ca. |